

Procedure-Modular Termination Analysis



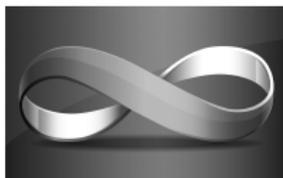
Cristina David
Daniel Kroening
Peter Schrammel



Motivation

Termination bugs:

- Hanging apps
- Zombie worker threads
- Denial-of-service attacks



State-of-the-art in termination analysis:

- Tremendous progress in recent years, but
 - Focus on small programs with complex termination arguments
 - SV-COMP Termination category (before 2017): avg. 20 lines per benchmark!
- Many tools use mathematical instead of machine numbers

Objective:

- Step towards practical termination analysis of large programs

Overview

Approach:

- Summary-based, context-sensitive, interprocedural
- Lexicographic ranking functions
- Universal termination and sufficient preconditions

2LS: static analysis tool for C programs:

- Synthesis-based program analysis
- Bit-precise reasoning

Evaluation:

- Benchmarks that are more than two orders of magnitude larger

TOPLAS 2018

Chen, David, Kroening, Schrammel, Wachter

Bit-Precise Procedure-Modular Termination Analysis

Overview

Termination Analyses

Universal termination:

- Result: terminating / potentially non-term. / non-terminating
- Decision problem

Conditional termination:

- Result: sufficient precondition for termination
- Inference problem

Example

(cf. <http://www.netlib.org/clapack/cblas/sasum.c>)

```
int h(int *sx, int n, int incx) {  
    int nincx = n * incx;  
    int stemp = 0;  
    for (int i=0; incx<0 ? i >= nincx : i <= nincx; i+=incx) {  
        stemp += sx[i];  
    }  
    return stemp;  
}
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- Why modular?

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- Why context-sensitive?
- Why modular?
- Why lexicographic ranking functions?

4	7	1	2
---	---	---	---

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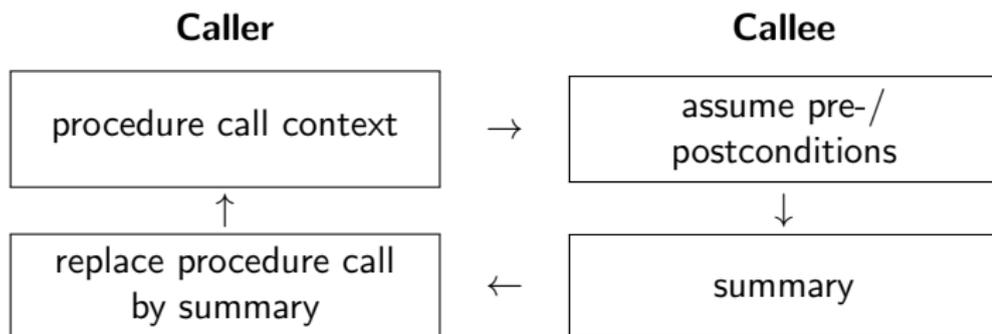
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3	8	4	2
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Summary-Based Interprocedural Analysis

- **Context:** relation over inputs and outputs from the caller's perspective
- **Summary:** relation over inputs and outputs from the callee's perspective



Example

```
unsigned f(unsigned z) {  
    unsigned w = 0;  
    if(z>0) w = h(z);  
    return w;  
}
```

```
unsigned h(unsigned y) {  
    unsigned x;  
    for (x=0; x<10; x+=y);  
    return x;  
}
```

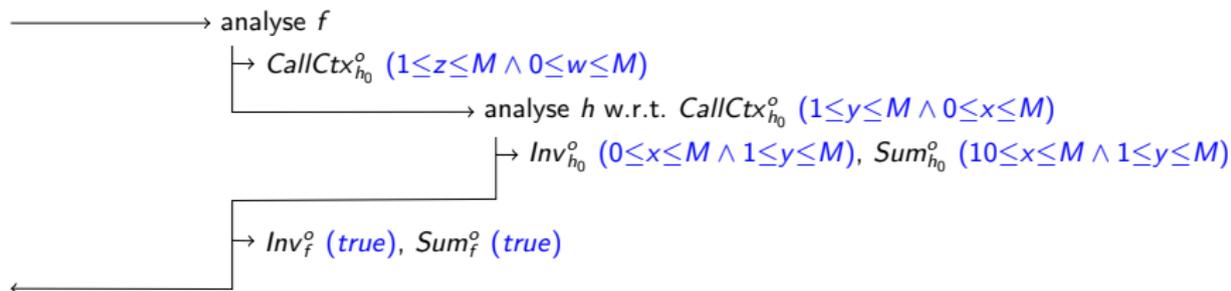
Example — Universal Termination

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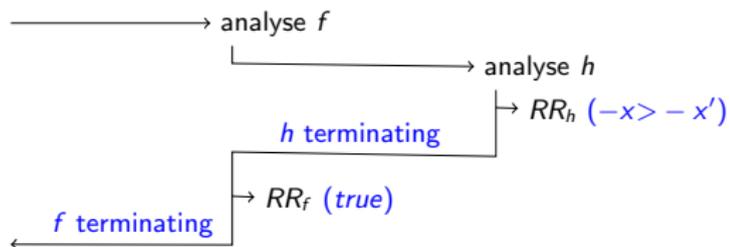
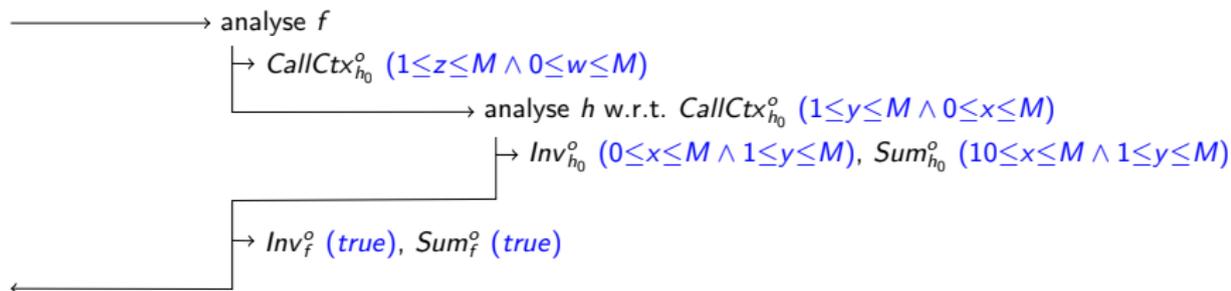
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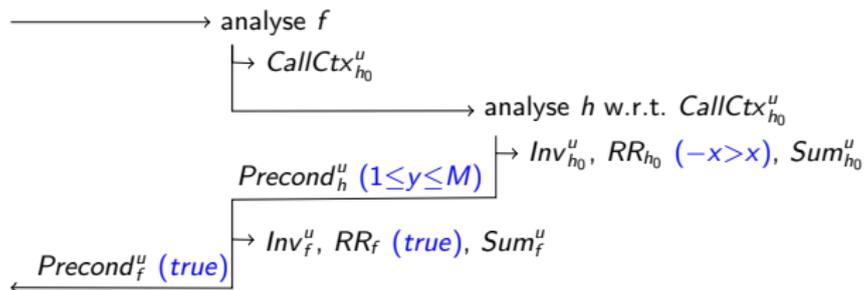
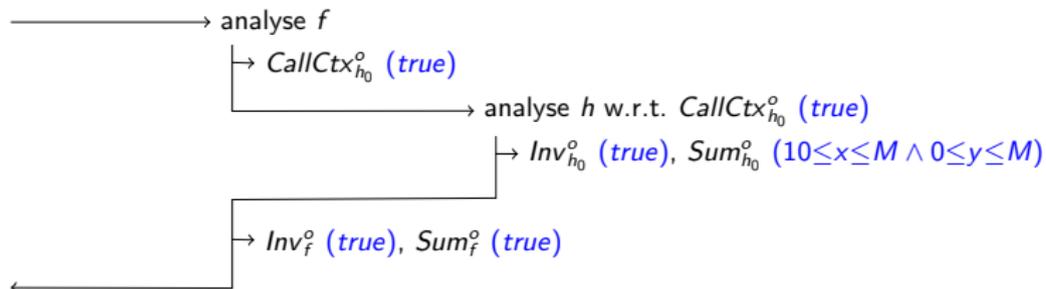
```



Example — Sufficient Preconditions

```
unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
```

```
unsigned h(unsigned y) {
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  for (x=0; x<10; x+=y);
  return x;
}
```



Synthesis-Based Program Analysis

2LS: A Static Analyser for C Programs

<http://www.cprover.org/2LS>

Built on CPROVER framework:

- Bit-precise analysis (including floating-point arithmetic)
- Reduction to propositional encoding and SAT solving

Concepts used:

- Logical specification of program analysis problems
- Template-based synthesis

Program Encoding

Non-recursive programs with multiple procedures

Procedure f : ($Init(x^{in}, x)$, $Trans(x, x')$, $Out(x, x^{out})$)

Program Encoding

Non-recursive programs with multiple procedures

Procedure f : ($Init(x^{in}, x)$, $Trans(x, x')$, $Out(x, x^{out})$)

```

unsigned f(unsigned z) {
  unsigned w = 0;            $w_0 = 0$ 
  if(z>0)                  $\wedge g_4 = z > 0$ 
    w = h(z);              $\wedge h_0((z), (r_{h_0})) \wedge w_1 = r_{h_0}$ 
                           $\wedge w_2^\phi = g_4 ? w_1 : w_0$ 
  return w;               $\wedge r_h = x_1^\phi$ 
}

unsigned h(unsigned y) {
  unsigned x;            $g_0 = true$ 
  for (x=0;            $\wedge x_0 = 0$ 
      x<10;            $\wedge g_1 = g_0 \wedge x_1^\phi = (ls_3 ? x_3^{lb} : x_0)$ 
      x+=y);          $\wedge g_2 = (x_1^\phi < 10 \wedge g_1)$ 
  return x;          $\wedge x_2 = x_1^\phi + y$ 
   $\wedge r_h = x_1^\phi$ 
}

```

Program Encoding

Non-recursive programs with multiple procedures

Procedure f : ($Init(x^{in}, x)$, $Trans(x, x')$, $Out(x, x^{out})$)

unsigned f(**unsigned** z) {

unsigned w = 0;

if(z>0)

 w = h(z);

return w;

}

$w_0 = 0$

$\wedge g_4 = z > 0$

$\wedge h_0((z), (r_{h_0})) \wedge w_1 = r_{h_0}$

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$g_0 = true$

$\wedge x_0 = 0$

$\wedge g_1 = g_0 \wedge x_1^\phi = (ls_3 ? x_3^{lb} : x_0)$

$\wedge g_2 = (x_1^\phi < 10 \wedge g_1)$

$\wedge x_2 = x_1^\phi + y$

$\wedge r_h = x_1^\phi$

Logical Specification of Program Analysis Problems

Safety verification:

$$\begin{aligned} \exists_2 Inv. \quad & \forall \mathbf{x}^{in}, \mathbf{x}, \mathbf{x}'. \\ & (Init(\mathbf{x}^{in}, \mathbf{x}) \implies Inv(\mathbf{x})) \wedge \\ & (Inv(\mathbf{x}) \wedge Trans(\mathbf{x}, \mathbf{x}') \implies Inv(\mathbf{x}')) \wedge \\ & (Inv(\mathbf{x}) \implies \neg Err(\mathbf{x})) \end{aligned}$$

(Blass and Gurevich '87, Grebenschikov et al '12, David et al '15, ...)

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Invariant inference:

$$\begin{aligned} \text{min Inv. } \forall \mathbf{x}, \mathbf{x}'. \\ & (\text{Init}(\mathbf{x}) \implies \text{Inv}(\mathbf{x})) \wedge \\ & (\text{Inv}(\mathbf{x}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies \text{Inv}(\mathbf{x}')) \end{aligned}$$

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Termination, ...

(Blass and Gurevich '87, Grebenschikov et al '12, David et al '15, ...)

Template-Based Synthesis

Reduction to first-order logic via templates, e.g. safety verification:

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Template-Based Synthesis

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$$\begin{aligned} \exists \mathbf{d}. \quad \forall \mathbf{x}, \mathbf{x}'. \quad & (\text{Init}(\mathbf{x}) \implies \mathcal{T}(\mathbf{x}, \mathbf{d})) \wedge \\ & (\mathcal{T}(\mathbf{x}, \mathbf{d}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies \mathcal{T}(\mathbf{x}', \mathbf{d})) \wedge \\ & (\mathcal{T}(\mathbf{x}, \mathbf{d}) \implies \neg \text{Err}(\mathbf{x})) \end{aligned}$$

where \mathbf{d} are template parameters.

(Graf & Saïdi CAV'97, ..., Reps et al, ... Brauer et al, ..., Srivastava et al, ...)

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- Abstract interpretation with large-block transformers
- Abstract domains implemented implicitly
- Drawback: Difficult to make efficient
 - We use strategy iteration (e.g. Gawlitza & Seidl, FMSD'14)

Invariants, Summaries, Calling Contexts

- **Invariant** Inv :

$$\begin{aligned} \min \quad & Inv^o. \forall \mathbf{x}^{in}, \mathbf{x}, \mathbf{x}'. \quad Init(\mathbf{x}^{in}, \mathbf{x}) \implies Inv^o(\mathbf{x}) \\ & \wedge \quad Inv^o(\mathbf{x}) \wedge Trans(\mathbf{x}, \mathbf{x}') \implies Inv^o(\mathbf{x}') \end{aligned}$$

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- **Summary** Sum^o :

$$\begin{aligned} \min \quad & Sum^o. \forall \mathbf{x}^{in}, \mathbf{x}, \mathbf{x}', \mathbf{x}^{out}. \\ & Init(\mathbf{x}^{in}, \mathbf{x}) \wedge Inv^o(\mathbf{x}') \wedge Out(\mathbf{x}', \mathbf{x}^{out}) \implies Sum^o(\mathbf{x}^{in}, \mathbf{x}^{out}) \end{aligned}$$

Invariants, Summaries, Calling Contexts

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- **Calling context** $CallCtx_{h_i}^o$ for procedure call h at call site i :

$$\begin{aligned} \min \text{CallCtx}_{h_i}^o. \forall \mathbf{x}, \mathbf{x}', \mathbf{x}^{p-in}_i, \mathbf{x}^{p-out}_i : \\ \text{Inv}^o(\mathbf{x}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies \text{CallCtx}_{h_i}^o(\mathbf{x}^{p-in}_i, \mathbf{x}^{p-out}_i) \end{aligned}$$

Termination Arguments, Preconditions

- Given Inv^o , **termination argument** RR :

$$\exists RR. \forall \mathbf{x}, \mathbf{x}' : Inv^o(\mathbf{x}) \wedge Trans(\mathbf{x}, \mathbf{x}') \implies RR(\mathbf{x}, \mathbf{x}')$$

with e.g. $RR(\mathbf{x}, \mathbf{x}') = r(\mathbf{x}) > r(\mathbf{x}') \wedge r(\mathbf{x}) > 0$

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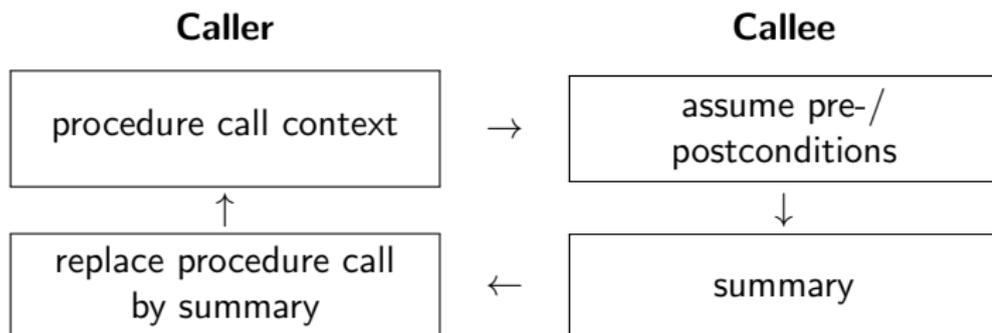
with e.g. $RR(\mathbf{x}, \mathbf{x}') = r(\mathbf{x}) > r(\mathbf{x}') \wedge r(\mathbf{x}) > 0$

- **Sufficient precondition for termination** $Precond^u \dots$

Interprocedural Analysis

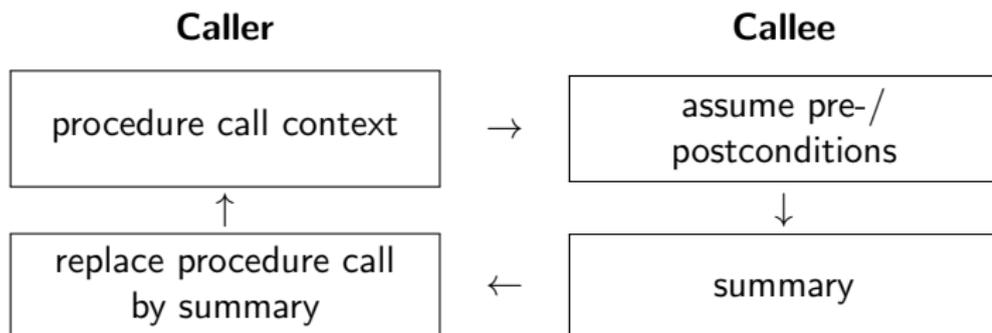
Summary-Based Interprocedural Analysis

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Summary-Based Interprocedural Analysis

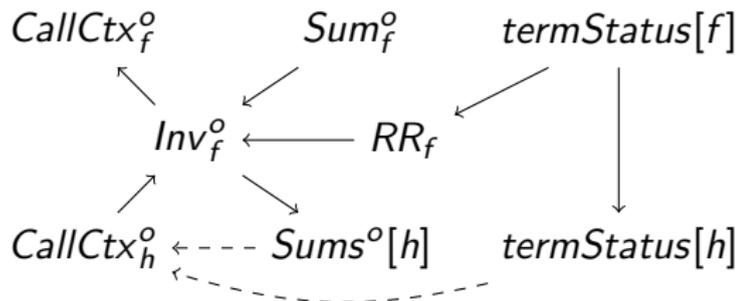
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Cyclically dependent predicates

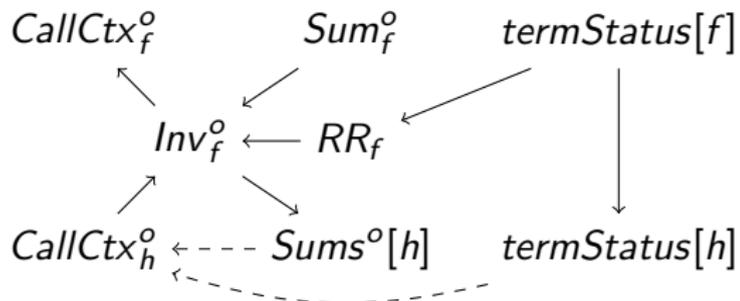
Universal Termination

Cyclically dependent predicates:



Decomposition of the Verification Problem

Cyclically dependent predicates:



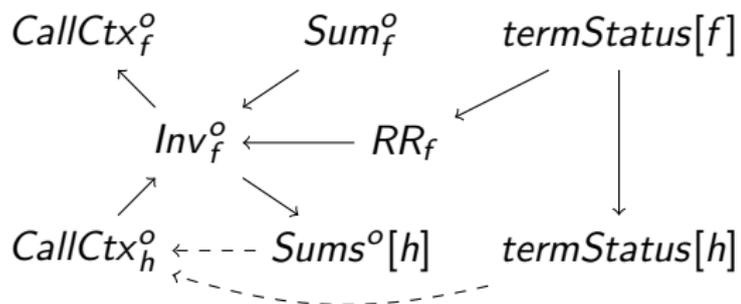
Decomposition into a sequence of subproblems

- Classical approach: Follow the call graph top-down

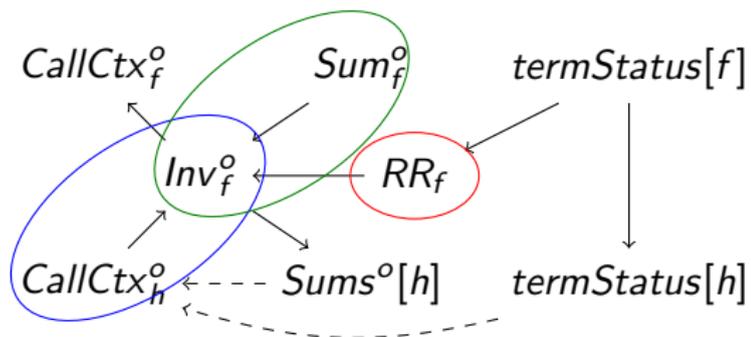
Soundness of the decomposition by

- soundness of the individual subproblems
- soundness of the combination of the subproblem results
- induction over the call graph traversal algorithm

Universal Termination



Universal Termination



- ① Calling contexts of procedure calls h in f
- ② Recurse
- ③ Invariants and summary of procedure f
- ④ Termination argument for procedure f
- ⑤ Determine termination status of f

Example – Bubble Sort

```
void sort(int n, int a[])
{
    __CPROVER_assume(n >= 0);

    for(int x=0; x < n-1; x++)
        for(int y=0; y < n-x-1; y++) // g
            if(a[y] > a[y+1])
                swap(a[y], a[y+1]);
}
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Termination arguments:

$$(\neg g \wedge (x < n - 1) \wedge \neg g' \implies (-1 \cdot (x - x') + 0 \cdot (y - y')) > 0) \wedge \\
 (g \wedge g' \implies (-1 \cdot (y - y') > 0)).$$

Lexicographic Linear Ranking Functions

Lexicographic ranking function $(R_n, R_{n-1}, \dots, R_1)$:

$$\begin{aligned} & \exists \Delta > 0, i \in [1, n] : \forall \mathbf{x}, \mathbf{x}' : \text{Inv}(\mathbf{x}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies \\ & \quad R_i(\mathbf{x}) > 0 \quad \text{(Bounded)} \\ & \wedge \quad R_i(\mathbf{x}) - R_i(\mathbf{x}') > \Delta \quad \text{(Decreasing)} \\ & \wedge \quad \forall j > i : R_j(\mathbf{x}) - R_j(\mathbf{x}') \geq 0 \quad \text{(Unaffected)} \end{aligned}$$

Lexicographic Linear Ranking Functions

Lexicographic ranking function $(R_n, R_{n-1}, \dots, R_1)$:

$$\begin{aligned} \exists \Delta > 0, i \in [1, n] : \forall \mathbf{x}, \mathbf{x}' : \text{Inv}(\mathbf{x}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies \\ & R_i(\mathbf{x}) > 0 \qquad \qquad \qquad \text{(Bounded)} \\ \wedge \quad R_i(\mathbf{x}) - R_i(\mathbf{x}') > \Delta \qquad \qquad \qquad \text{(Decreasing)} \\ \wedge \quad \forall j > i : R_j(\mathbf{x}) - R_j(\mathbf{x}') \geq 0 \qquad \qquad \text{(Unaffected)} \end{aligned}$$

Lexicographic Linear Ranking Functions

Lexicographic ranking function $(R_n, R_{n-1}, \dots, R_1)$:

$$\begin{aligned} & \exists \Delta > 0, i \in [1, n] : \forall \mathbf{x}, \mathbf{x}' : Inv(\mathbf{x}) \wedge Trans(\mathbf{x}, \mathbf{x}') \implies \\ & \quad R_i(\mathbf{x}) > 0 \quad \text{(Bounded)} \\ & \wedge R_i(\mathbf{x}) - R_i(\mathbf{x}') > 0 \quad \text{(Decreasing)} \\ & \wedge \forall j > i : R_j(\mathbf{x}) - R_j(\mathbf{x}') \geq 0 \quad \text{(Unaffected)} \end{aligned}$$

Lexicographic Linear Ranking Functions

Lexicographic ranking function $(R_n, R_{n-1}, \dots, R_1)$:

$$\begin{aligned} \exists \Delta > 0, i \in [1, n] : \forall \mathbf{x}, \mathbf{x}' : \text{Inv}(\mathbf{x}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies \\ & R_i(\mathbf{x}) > 0 \quad \text{(Bounded)} \\ \wedge \quad R_i(\mathbf{x}) - R_i(\mathbf{x}') > 0 \quad \text{(Decreasing)} \\ \wedge \quad \forall j > i : R_j(\mathbf{x}) - R_j(\mathbf{x}') \geq 0 \quad \text{(Unaffected)} \end{aligned}$$

Lexicographic ranking function $(R_n, R_{n-1}, \dots, R_1)$ over bitvectors:

$$\exists RR^n. \forall \mathbf{x}, \mathbf{x}' : \text{Inv}(\mathbf{x}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies RR^n(\mathbf{x}, \mathbf{x}')$$

with

$$RR^n(\mathbf{x}, \mathbf{x}') = \bigvee_{i=1}^n (R_i(\mathbf{x}) - R_i(\mathbf{x}') > 0 \wedge \bigwedge_{j=i+1}^n (R_j(\mathbf{x}) - R_j(\mathbf{x}') \geq 0))$$

Lexicographic Linear Ranking Functions

```
int x=1, y=1;
while(x>0) {
  if(y<10) x=nondet();
  else x--;
  if(y<100) y++;
}
```

$Trans((x, y), (x', y')) = \dots$

- 1 Start with $RR = false$, $n = 1$ components
- 2 Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- 3 Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- 4 Repeat from 2.

Lexicographic Linear Ranking Functions

```
int x=1, y=1;
while(x>0) {
  if(y<10) x=nondet();
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Lexicographic Linear Ranking Functions

```

int x=1, y=1;
while(x>0) {
    if(y<10) x=nondet();
    else x--;
    if(y<100) y++;
}

```

$Trans((x, y), (x', y')) = \dots$

$((x, y), (x', y')) = ((1, 100), (0, 100))$

- ① Start with $RR = false$, $n = 1$ components
- ② Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
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- ④ Repeat from 2.

Lexicographic Linear Ranking Functions

```

int x=1, y=1;
while(x>0) {
    if(y<10) x=nondet();
    else x--;
    if(y<100) y++;
}

```

$Trans((x, y), (x', y')) = \dots$
 $((x, y), (x', y')) = ((1, 100), (0, 100))$
 RR^1 corresponds to (x)

- ① Start with $RR = false$, $n = 1$ components
- ② Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- ③ Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- ④ Repeat from 2.

Lexicographic Linear Ranking Functions

```
int x=1, y=1;
while(x>0) {
  if(y<10) x=nondet();
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}
```

$Trans((x, y), (x', y')) = \dots$

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Lexicographic Linear Ranking Functions

```

int x=1, y=1;
while(x>0) {
    if(y<10) x=nondet();
    else x--;
    if(y<100) y++;
}

```

$Trans((x, y), (x', y')) = \dots$

$((x, y), (x', y')) = ((1, 1), (1001, 2))$

- ① Start with $RR = false$, $n = 1$ components
- ② Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- ③ Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- ④ Repeat from 2.

Lexicographic Linear Ranking Functions

```

int x=1, y=1;
while(x>0) {
  if(y<10) x=nondet();
  else x--;
  if(y<100) y++;
}

```

$Trans((x, y), (x', y')) = \dots$

$((x, y), (x', y')) = ((1, 1), (1001, 2))$
 RR^1 infeasible

- ① Start with $RR = false$, $n = 1$ components
- ② Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- ③ Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- ④ Repeat from 2.

Lexicographic Linear Ranking Functions

```
int x=1, y=1;
while(x>0) {
  if(y<10) x=nondet();
  else x--;
  if(y<100) y++;
}
```

$Trans((x, y), (x', y')) = \dots$

- 1 Start with $RR = false$, $n = 1$ components
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- 3 Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- 4 Repeat from 2.

Lexicographic Linear Ranking Functions

```

int x=1, y=1;
while(x>0) {
    if(y<10) x=nondet();
    else x--;
    if(y<100) y++;
}

```

$Trans((x, y), (x', y')) = \dots$

$((x, y), (x', y')) = ((1, 99), (0, 100))$

- ① Start with $RR = false$, $n = 1$ components
- ② Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- ③ Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- ④ Repeat from 2.

Lexicographic Linear Ranking Functions

```

int x=1, y=1;
while(x>0) {
    if(y<10) x=nondet();
    else x--;
    if(y<100) y++;
}

```

$Trans((x, y), (x', y')) = \dots$
 $((x, y), (x', y')) = ((1, 99), (0, 100))$
 RR^2 corresponds to $(-y, x)$

- ① Start with $RR = false$, $n = 1$ components
- ② Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- ③ Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- ④ Repeat from 2.

Lexicographic Linear Ranking Functions

```
int x=1, y=1;
while(x>0) {
  if(y<10) x=nondet();
  else x--;
  if(y<100) y++;
}
```

$Trans((x, y), (x', y')) = \dots$

- 1 Start with $RR = false$, $n = 1$ components
- 2 Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- 3 Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- 4 Repeat from 2.

Lexicographic Linear Ranking Functions

```

int x=1, y=1;
while(x>0) {
  if(y<10) x=nondet();
  else x--;
  if(y<100) y++;
}

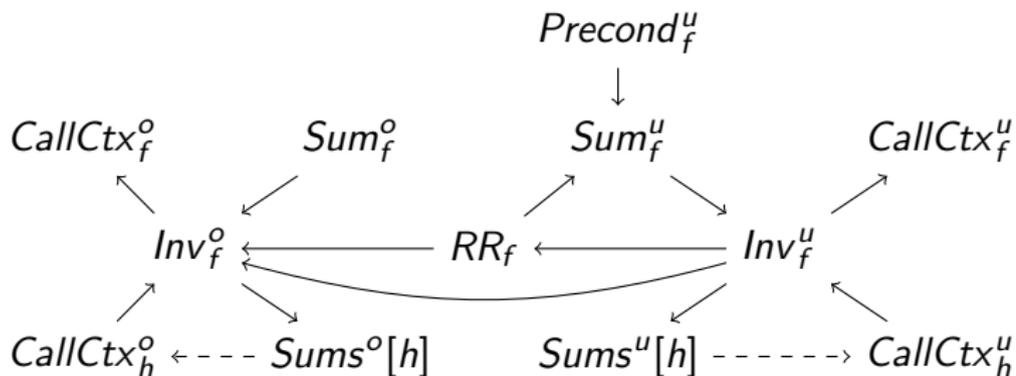
```

$Trans((x, y), (x', y')) = \dots$

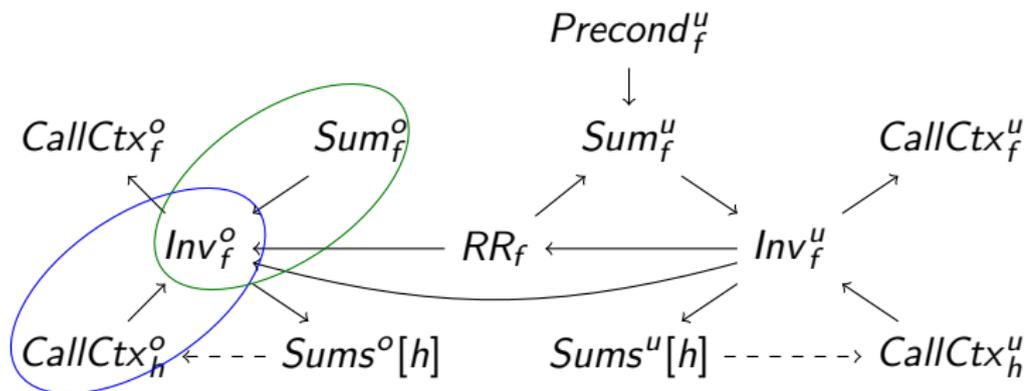
$((x, y), (x', y'))$ no more values
 RR^2 corresponds to $(-y, x)$

- ① Start with $RR = false$, $n = 1$ components
- ② Find values for $((x, y), (x', y'))$ that do not satisfy RR
 - If fails then RR is a valid termination argument
- ③ Find values for parameters of ranking function components
 - If fails then increase n
 - Otherwise instantiate RR
- ④ Repeat from 2.

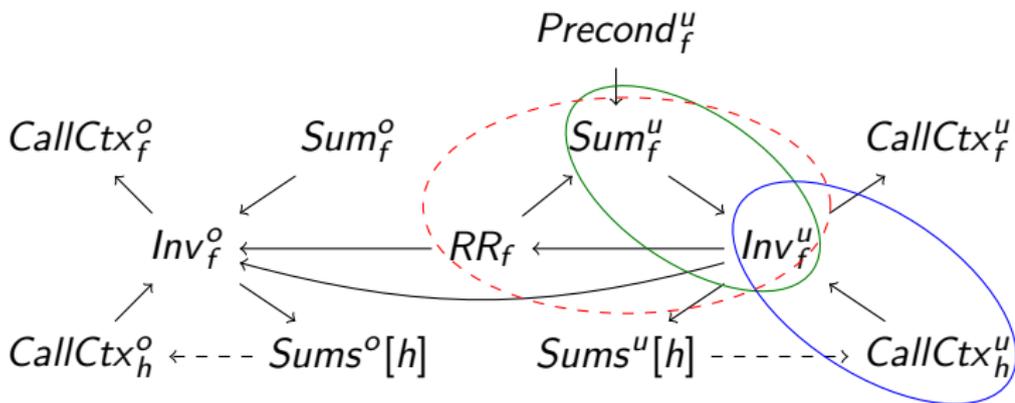
Sufficient Preconditions for Termination



Sufficient Preconditions for Termination



Sufficient Preconditions for Termination

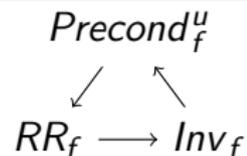


- ① ...
- ② Under-approximating calling contexts of procedure calls h in f
- ③ Recurse
- ④ Termination argument and sufficient preconditions for procedure f
- ⑤ Under-approximating invariants and summary of procedure f

Sufficient Preconditions for Termination

false is trivial sufficient precondition

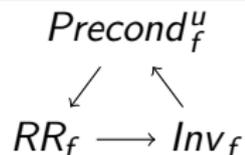
Want to find “maximal” (weakest) solutions



Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions



```

unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
  
```

```

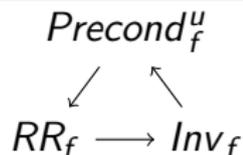
unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

(cf. Cook et al '08)

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions



```

unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
  
```

```

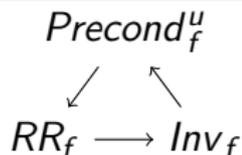
unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

- 1 Pick a valid input as candidate precondition, e.g. $y=0$

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions



```

unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
  
```

```

unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

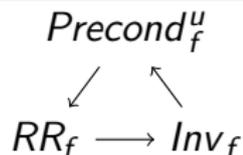
- 1 Pick a valid input as candidate precondition, e.g. $y=0$
- 2 Compute invariant $(x=0 \wedge y=0)$
and termination argument RR_f (not found)

(cf. Cook et al '08)

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions



```

unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
  
```

```

unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

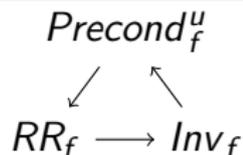
- 1 Pick a valid input as candidate precondition, e.g. $y=21$

(cf. Cook et al '08)

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions



```

unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
  
```

```

unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

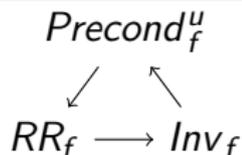
- 1 Pick a valid input as candidate precondition, e.g. $y=21$
- 2 Compute invariant $(0 \leq x \leq 42 \wedge y=21)$
and termination argument $RR_f (-x > -x')$

(cf. Cook et al '08)

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions



```

unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
  
```

```

unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

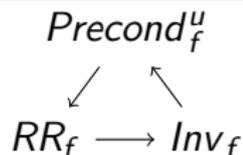
- 1 Pick a valid input as candidate precondition, e.g.
- 2 Compute invariant $(0 \leq x \leq 42 \wedge y = 21)$
and termination argument $RR_f (-x > -x')$
- 3 Compute partial precondition $Precond' = (1 \leq y \leq M)$
under-approximating all inputs that terminate under RR_f

(cf. Cook et al '08)

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions



```

unsigned f(unsigned z) {
  unsigned w = 0;
  if(z>0) w = h(z);
  return w;
}
  
```

```

unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

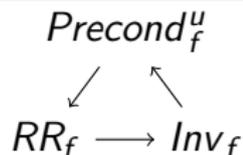
- ① Pick a valid input as candidate precondition, e.g.
 - If no such input found, $\text{Precond}_f^u = (1 \leq y \leq M)$
- ② Compute invariant $(0 \leq x \leq 42 \wedge y = 21)$
and termination argument $RR_f (-x > -x')$
- ③ Compute partial precondition $\text{Precond}' = (1 \leq y \leq M)$
under-approximating all inputs that terminate under RR_f

(cf. Cook et al '08)

Sufficient Preconditions for Termination

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```

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}
  
```

```

unsigned h(unsigned y) {
  unsigned x;
  for (x=0; x<10; x+=y);
  return x;
}
  
```

- 1 Pick a valid input as candidate precondition, e.g.
 - If no such input found, $\text{Precond}_f^u = (1 \leq y \leq M)$
- 2 Compute invariant $(0 \leq x \leq 42 \wedge y = 21)$
and termination argument $RR_f (-x > -x')$
- 3 Compute partial precondition $\text{Precond}' = (1 \leq y \leq M)$
under-approximating all inputs that terminate under RR_f

(cf. Cook et al '08)

Sufficient Preconditions for Termination

Under-approximations:

- Compute a sufficient precondition for termination by computing a necessary precondition for non-termination
- Given RR , solve:

$$\begin{aligned} \min \text{Precond}^{\tilde{u}}, \text{Inv}^{\tilde{u}} : \forall \mathbf{x}^{in}, \mathbf{x}, \mathbf{x}' : \\ \text{Precond}^{\tilde{u}}(\mathbf{x}^{in}) \wedge \text{Init}(\mathbf{x}^{in}, \mathbf{x}) \implies \text{Inv}^{\tilde{u}}(\mathbf{x}) \\ \wedge \text{Inv}^{\tilde{u}}(\mathbf{x}) \wedge \text{Trans}(\mathbf{x}, \mathbf{x}') \implies \text{Inv}^{\tilde{u}}(\mathbf{x}') \wedge \neg RR(\mathbf{x}, \mathbf{x}') . \end{aligned}$$

- $\text{Precond}^u := \neg \text{Precond}^{\tilde{u}}$

(cf. Cook et al '08)

Evaluation

Evaluation

Hypotheses:

- Modular termination analysis is fast
- Modular termination analysis is precise
- 2LS outperforms existing termination analysis tools
- 2LS' analysis is bit-precise
- 2LS computes usable preconditions for termination

Benchmarks:

- Product line benchmarks from SV-COMP
(597 benchmarks, 1.6 MLOC)
- Non-trivial procedural structure
(on average 67 procedures, 5.5 loops)

Modular termination analysis is fast

	expected	2LS IPTA	2LS MTA	TAN	Ultimate
terminating	264	249	26	18	50
non-terminating	333	320	333	3	324
potentially non-terminating	—	14	1	425	0
timed out	—	14	237	150	43
errors	—	0	0	1	180
total run time (h)	—	58.7	119.6	92.8	23.9

Timeout: 1800 s per benchmark

Modular termination analysis is precise

	expected	2LS IPTA	2LS MTA	TAN	Ultimate
terminating	264	249	26	18	50
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total run time (h)	—	58.7	119.6	92.8	23.9

Comparison with existing termination analysers

	expected	2LS IPTA	2LS MTA	TAN	Ultimate
terminating	264	249	26	18	50
non-terminating	333	320	333	3	324
potentially non-terminating	—	14	1	425	0
timed out	—	14	237	150	43
errors	—	0	0	1	180
total run time (h)	—	58.7	119.6	92.8	23.9

We also tried:

- AProVE, Loopus, FuncTion, HipTNT, ARMC, T2, KiTTel

Mathematical vs. Machine Integers

```
void f00(unsigned n) {
  for(unsigned x=0; x<=n; x++);
}
```

Mathematical ✓
Machine ×

```
void f01(unsigned x) {
  while(x>=10) x++;
}
```

Mathematical ×
Machine ✓

Benchmarks from Loopus tool (Sinn et al CAV'14):

	2LS	Loopus
terminating	2	15
potentially non-term.	9	0
timed out / unknown	4	0

Rationals vs. Floating-Point

```

void f00(float x) {
    __CPROVER_assume(
        FLT_MIN<=x && x<=FLT_MAX);
    while (x>0.0f)
        x *= 0.9f;
}

```

Rationals	×
Floating-point	×

```

void f01(float x) {
    __CPROVER_assume(
        FLT_MIN<=x && x<=FLT_MAX);
    while (x>0.0f)
        x *= 0.1f;
}

```

Rationals	×
Floating-point	✓

(with round-to-nearest/ties-to-even rounding mode)

SV-COMP Termination Category

1119 LOC on average in 2018! *

	2017				2018			
	total	term	nont	bug	total	term	nont	bug
Ultimate	1272	813	459	0	1725	1110	615	0
CPAChecker	821	396	425	4	1193	685	508	0
AProVE	520	458	62	0	906	838	68	0
2LS	927	580	347	34	1365	727	638	1

	2017	2018
Ultimate	36h	61h
CPAChecker	119h	150h
AProVE	167h	228h
2LS	16h	28h

* Thanks to Jera Hensel and other SV-COMP participants.

Preconditions for Termination

(From: <http://www.netlib.org/clapack/cblas/sasum.c>)

```
int f(int *sx, int n, int incx) {  
    int nincx = n * incx;  
    int stemp=0;  
    for (int i=0; incx<0 ? i >= nincx : i<= nincx;  
        i+=incx) {  
        stemp += sx[i-1];  
    }  
    return stemp;  
}
```

Sufficient precondition for termination: `incx != 0`

Conclusions

Limitations and Future Work

Language features:

- Recursion
- Dynamically allocated data structures
- Strings and arrays
- Concurrency

Analysis precision:

- Template refinement

Analyses and applications:

- Non-termination (Malík et al, TACAS'18)
- Sufficient preconditions for non-termination
- Cost analysis

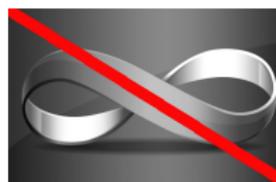
Wrap-up

Summary:

- Interprocedural termination analysis using synthesis-based program analysis approach
- Evaluation on larger benchmarks

Ongoing work:

- Extend to dynamically allocated data structures
- Template refinement



TOPLAS 2018

Chen, David, Kroening, Schrammel, Wachter

Bit-Precise Procedure-Modular Termination Analysis

2LS analysis tool for C programs: www.cprover.org/2LS

- Safety verification and refutation (SAS'15, TACAS'16, ATVA'17)
- (Non-)termination (ASE'15, TOPLAS'18, TACAS'18)

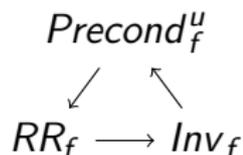
Extra Slides

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions

Bootstrapping:



- 1 Pick a valid input as candidate precondition
 - If no such input found, then candidate precondition is a sufficient precondition $Precond_f^u$
- 2 Compute invariant and termination argument RR_f under this precondition
 - If does not terminate, exclude input from candidate precondition and repeat from 1.
- 3 Compute partial precondition $Precond'$ under-approximating all inputs that terminate under RR_f
- 4 Add $Precond'$ to candidate precondition, repeat from 1.

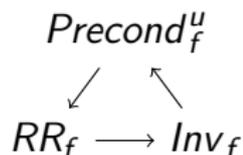
(cf. Cook et al '08)

Sufficient Preconditions for Termination

false is trivial sufficient precondition

Want to find “maximal” (weakest) solutions

Bootstrapping:



- ① Pick a valid input as candidate precondition
 - If no such input found, then candidate precondition is a sufficient precondition Precond_f^u
- ② Compute invariant and termination argument RR_f under this precondition
 - If does not terminate, exclude input from candidate precondition and repeat from 1.
- ③ Compute partial precondition $\text{Precond}'$ under-approximating all inputs that terminate under RR_f
- ④ Add $\text{Precond}'$ to candidate precondition, repeat from 1.

(cf. Cook et al '08)

Implementation Details

Solver backend:

- One SAT solver instance per procedure (plus helper solvers)
- Many incremental calls

Summary re-use:

- Only recurse if available summaries $Sums[h]$ are incompatible with $CallCtx_h$ at current call site

Issues:

- Bitvector extension
- Coefficient refinement
- Bounding iterations (where sound) and number of lexicographic components